

# A unified design of energy stable schemes with variable steps for fractional gradient flows and nonlinear integro-differential equations

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# Outline

- 1 Background
- 2 Discrete gradient structure
- 3 Application to time fractional Swift-Hohenberg model
- 4 Application to time fractional sine-Gordon model
- 5 Conclusion

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# Gradient flows

- Various physical and engineering problems are modeled by PDEs taking the form of gradient flows.
- Typical examples: interface dynamics <sup>1</sup>, crystallization <sup>2</sup>, pattern formation <sup>3</sup>.

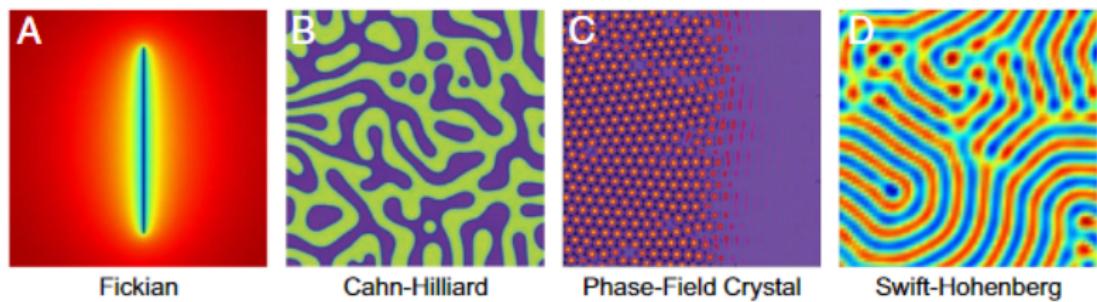


Figure 1: Representative gradient flows. (From *PNAS*, Vol. 119, No. 23, 2022)

<sup>1</sup> G. Boussinot, E. Brener, Phys. Rev. E, 88 (2013), 022406.

<sup>2</sup> K. Elder, N. Provatas, J. Berry, P. Stefanovic, M. Grant, Phys. Rev. B, 75 (2007), 064107.

<sup>3</sup> L. Coelho, E. Vitral, J. Pontes, N. Mangiavacchi, Phys. D, (2021), 427.

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- Energy dissipation law

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- Multiscale time behavior: fast-to-slow change during long-time simulation.

# Numerical methods for gradient flows

Key concerns: **energy stability, accuracy, efficiency.**

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- Convex-splitting (D. Eyre, MRS Proc, 1998)
- Stabilization (C. Xu, T. Tang, SINUM, 2006)
- Invariant energy quadratization (X. Yang, JCP, 2016)
- Scalar auxiliary variable (J. Shen, J. Xu, J. Yang, JCP, 2018)
- Operator-splitting (Y. Cheng, JCP, 2015)
- Exponential time differencing (X. Li, L. Ju, X. Meng, CiCP, 2019)
- ...

# Time fractional gradient flows

- Time fractional models: describe diffusion with memory effect <sup>4</sup>.

---

<sup>4</sup>T. Solomon, E. Weeks, H. Swinney, Phys. Rev. Lett, 71 (1993).

<sup>5</sup>Z. Li, H. Wang, D. Yang, J. Comput. Phys, 347 (2017), 20-38.

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- The Riemann-Liouville fractional integral of order  $\beta > 0$

$$\mathcal{I}^\beta v(t) = \int_0^t \omega_\beta(t-s)v(s)ds, \quad \text{with } \omega_\beta(t) = t^{\beta-1}/\Gamma(\beta). \quad (4)$$

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# Numerical methods for time fractional gradient flows

- L1-stabilized scheme (T. Tang, H. Yu, T. Zhou, SISC, 2020)  
**Energy boundedness**
- L2-SAV and L2-IMEX schemes (C. Quan, B. Wang, JCP, 2022)  
**Energy boundedness**
- CQ scheme (S. Karaa, SINUM, 2021)  
**Energy boundedness**
- BDF-SAV scheme (H. Zhang, X. Jiang, Nonlinear Dyn, 2020)  
**Modified energy dissipation law**
- L1-stabilized and L1-SAV schemes (Z. Liu, X. Li, J. Huang, NMPDE, 2021)  
**Modified energy dissipation law**
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Developed using the uniform time step sizes.

# Adaptive time strategy

- **Initial singularity** of time fractional differential equations.

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- Multiscale time behavior in long-time simulation.

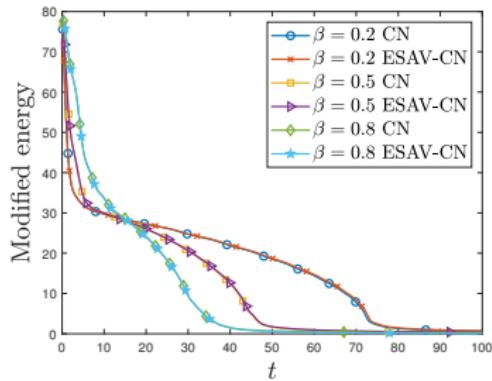


Figure 2: Energies with different fractional index.

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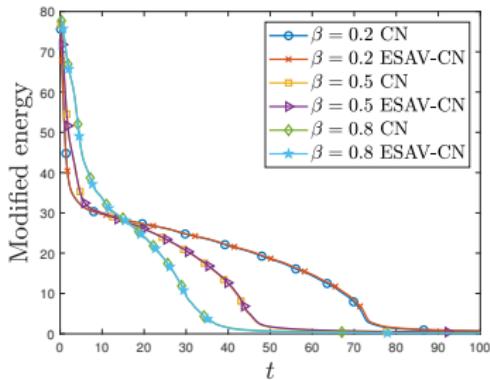


Figure 2: Energies with different fractional index.

- Practical way: Energy stable schemes with variable time steps

# Variable-step schemes for time fractional gradient flows

- L1 type schemes
  - ▶ L1 scheme for **TFAC** (B. Ji, H.-L. Liao, L. Zhang, ACM, 2020).
  - ▶ L1-ExSAV scheme for **TFAC** (D. Hou, C. Xu, SISC, 2021).
  - ▶ L1-ESAV scheme for **TFAC&TFCH** (Y. Yu, J. Zhang, R. Qin, JSC, 2023).
- L2- $1_\sigma$  type schemes
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  - ▶ L2- $1_\sigma$ -ExSAV scheme for **TFMBE** (D. Hou, C. Xu, JSC, 2022).
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Further: Asymptotic compatible discrete energy dissipation law ?

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One way: Positive-definiteness → Energy boundedness

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Another way: Discrete gradient structure

## Discrete gradient structure (DGS) view

- For  $\vec{x}^k = (x_1, x_2, \dots, x_k)^T$  and a discrete temporal differential operator  $D_\tau \vec{x}^k$ , it seeks  $c^* > 0$ , two nonnegative quadratic functionals  $P$  and  $Q$ , such that

$$x_k D_\tau \vec{x}^k = \textcolor{red}{P}[\vec{x}^k] - \textcolor{red}{P}[\vec{x}^{k-1}] + \textcolor{blue}{c^*} x_k^2 + \textcolor{red}{Q}[\vec{x}^k]. \quad (5)$$

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# Fractional nonlinear integro-differential models

- Various physical processes in viscoelastic materials characterized by the **non-linear integro-differential equations**<sup>8,9</sup>.

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- Consider the fractional integro-differential models with nonlinear memory

$$\frac{\partial u}{\partial t} + \mathcal{I}^\alpha \mu = 0, \quad \text{with } \mu = -\Delta u + f(u). \quad (6)$$

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- Many related numerical methods, see the monograph [Brunner, Cambridge University Press, 2004].

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# Motivations

- A unified DGS for nonuniform integral averaged formulae of time fractional derivative and integral

$$\mathcal{D}_t^\alpha u(t), \quad \mathcal{I}^\beta u(t).$$

- Variable-step energy stable schemes for time fractional gradient flow and nonlinear integro-differential equation

$$\mathcal{D}_t^\alpha u = \mathcal{G}\mu, \quad \frac{\partial u}{\partial t} + \mathcal{I}^\alpha \mu = 0.$$

- Energy stability analysis of SAV-based variable-step numerical schemes.

# Integral averaged formulae

- Consider  $0 = t_1 < t_2 < \dots < t_N = T$  with the step-sizes  $\tau_n = t_n - t_{n-1}$  for  $1 \leq n \leq N$ . Denote by  $r_n = \tau_n / \tau_{n-1}$  the adjacent step-size ratio.
- For any grid function  $v^n = v(t_n)$ , let  $\delta_\tau v^n = v^n - v^{n-1}$ ,  $\partial_\tau v^n = \delta_\tau v^n / \tau_n$  and  $v^{n-\frac{1}{2}} = (v^n + v^{n-1})/2$ .
- $\Pi_1 v$ : piecewise-linear interpolation on each subinterval  $[t_{n-1}, t_n]$ , the integral averaged formula for the Caputo derivative

$$\mathcal{D}_\tau^\alpha v^n = \frac{1}{\tau_n} \int_{t_{n-1}}^{t_n} \int_0^t \omega_{1-\alpha}(t-s) (\Pi_1 v(s))' ds dt = \sum_{j=1}^n c_{n-j}^{(1-\alpha,n)} \delta_\tau v^j. \quad (7)$$

- The discrete convolution kernels  $c_{n-j}^{(\alpha,n)}$  are given by

$$c_{n-j}^{(\alpha,n)} = \frac{1}{\tau_n \tau_j} \int_{t_{n-1}}^{t_n} \int_{t_{j-1}}^{\min\{t, t_j\}} \omega_\alpha(t-s) ds dt, \quad \text{for } 1 \leq j \leq n. \quad (8)$$

# Integral averaged formulae

- $\Pi_0 v$ : piecewise-constant interpolation on each subinterval  $[t_{n-1}, t_n]$ , the integral averaged formula for the Riemann-Liouville fractional integral

$$\mathcal{I}_\tau^\beta \bar{v}^n = \frac{1}{\tau_n} \int_{t_{n-1}}^{t_n} \int_0^t \omega_\beta(t-s) \Pi_0 v(s) ds dt = \sum_{j=1}^n c_{n-j}^{(\beta,n)} \tau_j \bar{v}^j, \quad (9)$$

where the piecewise-constants  $\bar{v}^n$  are flexible according to the problem.

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# Modified convolution kernels of nonuniform integral averaged formulae

- It is observed that

$$c_0^{(\alpha,n)} - c_1^{(\alpha,n)} = \frac{r_n}{\Gamma(2+\alpha)\tau_n^{1-\alpha}} [1 + 1/r_n + 1/r_n^{1+\alpha} - (1 + 1/r_n)^{1+\alpha}].$$

Thus  $c_0^{(\alpha,n)} > c_1^{(\alpha,n)}$  when  $\alpha \rightarrow 0$  but  $c_0^{(\alpha,n)} < c_1^{(\alpha,n)}$  when  $\alpha \rightarrow 1$ .

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- Denote

$$\hat{c}_0^{(\alpha,n)} = 2c_0^{(\alpha,n)} \quad \text{and} \quad \hat{c}_{n-j}^{(\alpha,n)} = c_{n-j}^{(\alpha,n)} \quad \text{for } 1 \leq j \leq n-1. \quad (10)$$

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- Such that

$$\hat{c}_0^{(\alpha,n)} > \hat{c}_1^{(\alpha,n)} > \hat{c}_2^{(\alpha,n)} > \dots > \hat{c}_{n-1}^{(\alpha,n)}.$$

# Properties of modified kernels $\hat{c}_{n-j}^{(\alpha,n)}$

The three algebraic properties of the modified kernels  $\hat{c}_{n-j}^{(\alpha,n)}$  are listed below.

## Theorem 1

For  $0 < \alpha < 1$ , the auxiliary kernels  $\hat{c}_{n-j}^{(\alpha,n)}$  defined in (10) satisfy

(1)  $\hat{c}_{n-j-1}^{(\alpha,n)} \geq \hat{c}_{n-j}^{(\alpha,n)} > 0$  for  $1 \leq j \leq n-1$ ;

If the adjacent step-size ratios  $r_{n+1}$  and  $r_n$  for  $n \geq 2$  fulfill the following relation

$$r_{n+1} \geq r_\alpha(r_n) = \left[ \frac{2h(r_n) - h(2r_n)}{r_n^\alpha (4 - 2^{1+\alpha})} \right]^{\frac{1}{\alpha}}, \quad (11)$$

then the auxiliary kernels  $\hat{c}_{n-j}^{(\alpha,n)}$  satisfy

(2)  $\hat{c}_{n-1-j}^{(\alpha,n-1)} > \hat{c}_{n-j}^{(\alpha,n)}$  for  $1 \leq j \leq n-1$ ;

(3)  $\hat{c}_{n-2-j}^{(\alpha,n-1)} - \hat{c}_{n-1-j}^{(\alpha,n-1)} > \hat{c}_{n-j-1}^{(\alpha,n)} - \hat{c}_{n-j}^{(\alpha,n)}$  for  $1 \leq j \leq n-2$ .

## Technical lemma

For given  $n \geq 2$  and a positive sequence  $\omega_{n-j}^{(n)} (1 \leq j \leq n)$ , introduce

$$\hat{\omega}_0^{(n)} = (2 - \theta) \omega_0^{(n)}, \quad \theta \in [0, 2),$$

$$\hat{\omega}_{n-j}^{(n)} = \omega_{n-j}^{(n)}, \quad 1 \leq j \leq n - 1.$$

### Lemma 1 [H.-L. Liao, N. Liu, X. Zhao, arXiv, 2022]

If the modified kernels  $\hat{\omega}_{n-j}^{(n)}$  satisfy:

$$(1) \hat{\omega}_{n-j-1}^{(n)} \geq \hat{\omega}_{n-j}^{(n)},$$

$$(2) \hat{\omega}_{n-1-j}^{(n-1)} \geq \hat{\omega}_{n-j}^{(n)}$$

$$(3) \hat{\omega}_{n-2-j}^{(n-1)} - \hat{\omega}_{n-1-j}^{(n-1)} \geq \hat{\omega}_{n-1-j}^{(n)} - \hat{\omega}_{n-j}^{(n)}, \text{ then}$$

$$2q_n \sum_{j=1}^n \omega_{n-j}^{(n)} q_j = G[\vec{q}_n] - G[\vec{q}_{n-1}] + \theta \omega_0^{(n)} q_n^2 + Y[\vec{q}_n], \quad \text{for } n \geq 1. \quad (12)$$

## Theorem 2 (DGS of nonuniform integral averaged formulae)

Under the step-size ratio constraint (11), we have the following discrete gradient structure of the integral averaged formulae (7) and (9)

$$\left\langle v_n, \sum_{j=1}^n c_{n-j}^{(\alpha,n)} v_j \right\rangle = \mathcal{F}_\alpha[\vec{v}_n] - \mathcal{F}_\alpha[\vec{v}_{n-1}] + \mathcal{R}_\alpha[\vec{v}_n], \quad \text{for } n \geq 2. \quad (13)$$

$$\begin{aligned} \mathcal{F}_\alpha[\vec{v}_n] &= \frac{1}{2} \sum_{j=1}^{n-1} \left( \hat{c}_{n-j-1}^{(\alpha,n)} - \hat{c}_{n-j}^{(\alpha,n)} \right) \left\| \sum_{k=j+1}^n v_k \right\|^2 + \frac{1}{2} \hat{c}_{n-1}^{(\alpha,n)} \left\| \sum_{k=1}^n v_k \right\|^2, \\ \mathcal{R}_\alpha[\vec{v}_n] &= \frac{1}{2} \sum_{j=1}^{n-2} \left( \hat{c}_{n-j-2}^{(\alpha,n-1)} - \hat{c}_{n-j-1}^{(\alpha,n-1)} - \hat{c}_{n-j-1}^{(\alpha,n)} + \hat{c}_{n-j}^{(\alpha,n)} \right) \left\| \sum_{k=j+1}^{n-1} v_k \right\|^2 \\ &\quad + \frac{1}{2} \left( \hat{c}_{n-2}^{(\alpha,n-1)} - \hat{c}_{n-1}^{(\alpha,n)} \right) \left\| \sum_{k=1}^{n-1} v_k \right\|^2. \end{aligned}$$

- DGS → the positive-definiteness of the nonuniform integral averaged formulae
- The lower bound of  $r_n$  is less than 1; no requirement for the upper bound

# Comparison

- Algebraic convexity in Theorem 1

$$\hat{c}_{n-2-j}^{(\alpha,n-1)} - \hat{c}_{n-1-j}^{(\alpha,n-1)} > \hat{c}_{n-j-1}^{(\alpha,n)} - \hat{c}_{n-j}^{(\alpha,n)}$$

# Comparison

- Algebraic convexity in Theorem 1

$$\hat{c}_{n-2-j}^{(\alpha, n-1)} - \hat{c}_{n-1-j}^{(\alpha, n-1)} > \hat{c}_{n-j-1}^{(\alpha, n)} - \hat{c}_{n-j}^{(\alpha, n)}$$

- Geometric convexity in [H.-L. Liao, N. Liu, P. Lyu, SINUM, 2023]

$$\hat{c}_{n-2-j}^{(\alpha, n-1)} \hat{c}_{n-j}^{(\alpha, n)} \geq \hat{c}_{n-1-j}^{(\alpha, n-1)} \hat{c}_{n-j-1}^{(\alpha, n)}.$$

# Comparison

- Algebraic convexity in Theorem 1

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- A different DGS under another step-size ratio restriction

$$r_{n+1} \geq \hat{r}_\alpha(r_n) = \left[ \frac{(2^\alpha - 1)h(r_n)}{h(2r_n) - 2h(r_n)} \right]^{\frac{1}{1-\alpha}}. \quad (14)$$

# Comparison

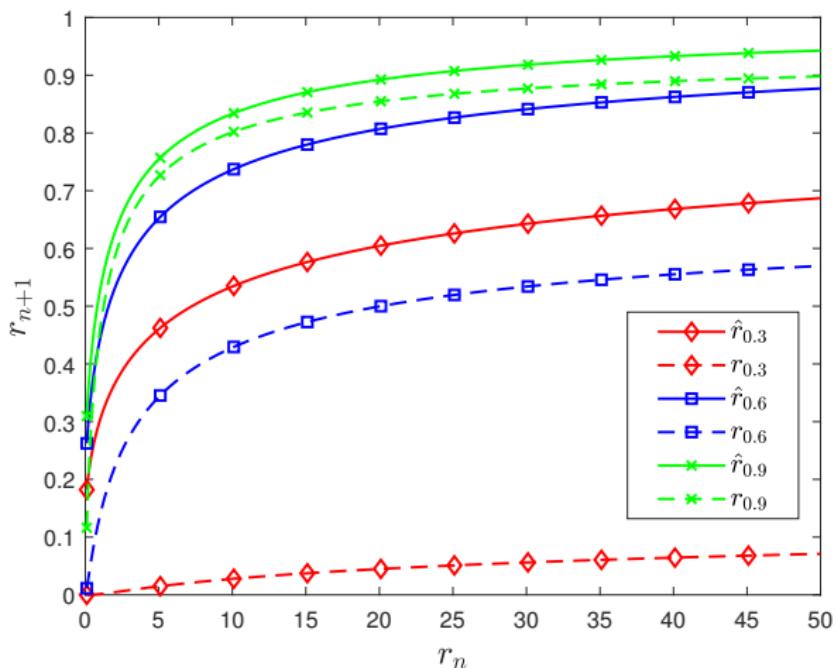


Figure 3: Comparisons of the step-size ratio constraints (11) with (14).

# Outline

- 1 Background
- 2 Discrete gradient structure
- 3 Application to time fractional Swift-Hohenberg model
- 4 Application to time fractional sine-Gordon model
- 5 Conclusion

# Time fractional Swift-Hohenberg (TFSH) model

- Consider the TFSH model of order  $\alpha \in (0, 1)$

$$\mathcal{D}_t^\alpha u = -\mu, \quad (\mathbf{x}, t) \in \Omega \times (0, T] \quad (15)$$

subjected to the periodic boundary conditions.

- $u(\mathbf{x}, t)$ : the density field of atoms in a binary mixture on the domain  $\Omega$ .
- Free energy  $E[u]$

$$E[u] = \int_{\Omega} \frac{1}{2} u(1 + \Delta)^2 u + F(u) d\mathbf{x}, \text{ with } F(u) = \frac{1}{4}u^4 - \frac{g}{3}u^3 + \frac{\epsilon}{2}u^2. \quad (16)$$

- $g, \epsilon$ : two nonnegative physical parameters.

## Variable-step CN scheme for TFSH model

- Using the integral averaged formula for Caputo derivative, the variable-step Crank-Nicoslon (CN) scheme

$$\mathcal{D}_\tau^\alpha u^n = -\mu^{n-\frac{1}{2}}, \quad \text{with } \mu^{n-\frac{1}{2}} = (1 + \Delta)^2 u^{n-\frac{1}{2}} + \Psi(u^n, u^{n-1}). \quad (17)$$

- The nonlinear term  $f(u) = F'(u)$  is implicitly treated

$$\begin{aligned}\Psi(u^n, u^{n-1}) &= \frac{F(u^n) - F(u^{n-1})}{u^n - u^{n-1}} \\ &= \frac{1}{2} u^{n-\frac{1}{2}} [(u^n)^2 + (u^{n-1})^2] - g \frac{(u^n)^2 + u^n u^{n-1} + (u^{n-1})^2}{3} - \epsilon u^{n-\frac{1}{2}}.\end{aligned}$$

- The CN scheme (17) is uniquely solvable when  $\tau_n \leq \sqrt[\alpha]{\frac{6}{\Gamma(3-\alpha)(g^2+3\epsilon)}}.$

# Energy dissipation law of variable-step CN scheme

Taking the inner product of variable-step CN scheme (17) with  $\delta_\tau u^n$ .

$$\begin{aligned}\langle \mathcal{D}_\tau^\alpha u^n, \delta_\tau u^n \rangle &= \left\langle \sum_{j=1}^n c_{n-j}^{(\alpha,n)} \delta_\tau u^n, \delta_\tau u^n \right\rangle \\ &= \mathcal{F}_{1-\alpha}[\delta_\tau u^n] - \mathcal{F}_{1-\alpha}[\delta_\tau u^{n-1}] + \mathcal{R}_{1-\alpha}[\delta_\tau u^n], \\ \langle \mu^{n-\frac{1}{2}}, \delta_\tau u^n \rangle &= E[u^n] - E[u^{n-1}].\end{aligned}$$

## Theorem 3

Under the step-size ratio restriction (11), the variable-step CN scheme (17) preserves the following discrete energy dissipation law

$$\partial_\tau E_\alpha[u^n] = -\frac{1}{\tau_n} \mathcal{R}_{1-\alpha}[\delta_\tau u^n], \quad \text{for } 1 \leq n \leq N, \quad (18)$$

where the modified energy  $E_\alpha[\cdot] = E[u^n] + \mathcal{F}_{1-\alpha}[\delta_\tau u^n]$ .

# Asymptotic compatibility of variable-step CN scheme

- As  $\alpha \rightarrow 1^-$ ,  $c_0^{(1-\alpha,n)} \rightarrow 1/\tau_n$  and  $c_j^{(1-\alpha,n)} \rightarrow 0$  for  $1 \leq j \leq n-1$ .

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- As  $\alpha \rightarrow 1^-$ ,  $c_0^{(1-\alpha,n)} \rightarrow 1/\tau_n$  and  $c_j^{(1-\alpha,n)} \rightarrow 0$  for  $1 \leq j \leq n-1$ .
- The CN scheme (17) reduces to the CN scheme for classical SH model

$$\partial_\tau u^n = -\mu^{n-\frac{1}{2}}, \quad \text{for } n \geq 1, \quad (19)$$

which holds that

$$\partial_\tau E[u^n] = -\|\mu^{n-\frac{1}{2}}\|^2, \quad \text{for } n \geq 1. \quad (20)$$

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- Moreover,  $\hat{c}_0^{(1-\alpha,n)} \rightarrow 2/\tau_n$  and  $\hat{c}_j^{(1-\alpha,n)} \rightarrow 0$  for  $1 \leq j \leq n-1$ .

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- The energy dissipation law (18) reduces to

$$\partial_\tau E[u^n] = -\|\partial_\tau u^n\|^2, \quad \text{for } n \geq 1,$$

which is the same as (20).

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which is the same as (20).

- The **discrete energy dissipation law** of variable-step CN scheme is **asymptotically compatible**.

# Variable-step ESAV-CN scheme for TFSH model

- The proposed DGS is also useful to develop **SAV-based variable-step energy stable linear schemes**.
- Introduce an exponential SAV (ESAV, see, Z. Liu, X. Li, SISC, 2020)

$$s(t) = \exp(E_1[u]) = \exp\left(\int_{\Omega} \frac{1}{4}u^4 - \frac{g}{3}u^3 + \frac{\epsilon}{2}u^2 d\mathbf{x}\right),$$

and denote  $\sigma(u, s) = \frac{s(t)}{\exp(E_1[u])} f(u)$ .

- The TFSH model (15) is transformed into the expanded system

$$\mathcal{D}_t^\alpha u = -\mu, \tag{21a}$$

$$\mu = (1 + \Delta)^2 u + \sigma(u, s), \tag{21b}$$

$$(\ln s)_t = \langle \sigma(u, s), u_t \rangle. \tag{21c}$$

# Variable-step ESAV-CN scheme for TFSH model

- Using the integral averaged formula for (21a) and the standard Crank-Nicolson discretization for (21c).
- Variable-step ESAV Crank-Nicolson (ESAV-CN) scheme

$$\mathcal{D}_\tau^\alpha u^n = -\mu^{n-\frac{1}{2}}, \quad (22a)$$

$$\mu^{n-\frac{1}{2}} = (1 + \Delta)^2 u^{n-\frac{1}{2}} + \sigma(\bar{u}^{n-\frac{1}{2}}, \bar{s}^{n-\frac{1}{2}}), \quad (22b)$$

$$\ln s^n - \ln s^{n-1} = \left\langle \sigma(\bar{u}^{n-\frac{1}{2}}, \bar{s}^{n-\frac{1}{2}}), u^n - u^{n-1} \right\rangle. \quad (22c)$$

- $\bar{u}^{n-\frac{1}{2}} = (1 + \frac{r_n}{2})u^{n-1} - \frac{r_n}{2}u^{n-2}$  and  $\bar{s}^{n-\frac{1}{2}} = (1 + \frac{r_n}{2})s^{n-1} - \frac{r_n}{2}s^{n-2}$  are explicit second order approximations for  $u(t_{n-1/2})$  and  $s(t_{n-1/2})$ .

# Energy dissipation law of variable-step ESAV-CN scheme

Taking the inner product of (22a) and (22b) with  $\delta_\tau u^n$ .

$$\langle \mathcal{D}_\tau^\alpha u^n, \delta_\tau u^n \rangle = \mathcal{F}_{1-\alpha}[\delta_\tau u^n] - \mathcal{F}_{1-\alpha}[\delta_\tau u^{n-1}] + \mathcal{R}_{1-\alpha}[\delta_\tau u^n].$$

$$\langle \mu^{n-\frac{1}{2}}, \delta_\tau u^n \rangle = \frac{1}{2} (\|(1+\Delta)u^n\|^2 - \|(1+\Delta)u^{n-1}\|^2) + \ln s^n - \ln s^{n-1}.$$

## Theorem 4

If the step-size ratio constraint (11) is satisfied, the variable-step ESAV-CN scheme (22) preserves the energy dissipation law

$$\partial_\tau \tilde{E}_\alpha[u^n] = -\frac{1}{\tau_n} \mathcal{R}_{1-\alpha}[\delta_\tau u^n], \quad \text{for } 1 \leq n \leq N, \quad (23)$$

where the modified energy  $\tilde{E}_\alpha[\cdot]$  is defined as

$$\tilde{E}_\alpha[u^n] = \frac{1}{2} \|(1+\Delta)u^n\|^2 + \ln s^n + \mathcal{F}_{1-\alpha}[\delta_\tau u^n]. \quad (24)$$

# Asymptotic compatibility of variable-step ESAV-CN scheme

- As  $\alpha \rightarrow 1^-$ , the ESAV-CN scheme (22) reduces to the ESAV-based Crank-Nicolson scheme for the classical SH model.
- The **discrete energy dissipation law** is **asymptotically compatible** with the classical counterpart

$$\partial_\tau \hat{E} = -\|\partial_\tau u^n\|^2,$$

where  $\hat{E}[u^n] = \frac{1}{2}\|(1 + \Delta)u^n\|^2 + \ln s^n$ .

# Numerical experiments

## Example 1

(Convergence test). Consider a forced TFSH model:  $\mathcal{D}_t^\alpha u = -\mu + f(\mathbf{x}, t)$  until  $T = 1$  in the domain  $\Omega = (0, 2\pi)^2$  with parameters  $g = 1$  and  $\epsilon = 0.2$ . The exact solution  $u = t^\sigma \sin x \sin y / \Gamma(1 + \sigma)$ .

- Space: Fourier pseudo-spectral method.
- Time: graded mesh  $t_n = T(n/N)^\gamma$ . Optimal second-order when  $\gamma \geq \frac{2}{\sigma}$ .

## Numerical experiments

Table 1: Convergence rates of CN scheme and ESAV-CN scheme with  $(\alpha, \sigma) = (0.4, 0.6)$ .

	N	$\gamma = 2$		$\gamma = 2/\sigma$		$\gamma = 4$	
		$e(N)$	Rate	$e(N)$	Rate	$e(N)$	Rate
CN	80	3.90e-3	-	1.77e-4	-	2.00e-4	-
	160	1.69e-3	1.21	4.46e-5	2.01	5.01e-5	2.02
	320	7.34e-4	1.21	1.12e-5	2.00	1.26e-5	2.01
	640	3.19e-4	1.20	2.81e-6	2.00	3.15e-6	2.00
ESAV-CN	80	4.38e-3	-	1.09e-2	-	1.53e-2	-
	160	1.70e-3	1.37	2.84e-3	1.97	4.00e-3	1.97
	320	7.36e-4	1.21	7.30e-4	1.97	1.03e-3	1.97
	640	3.20e-4	1.20	1.86e-4	1.98	2.63e-4	1.98

## Numerical experiments

Table 2: Convergence rates of CN scheme and ESAV-CN scheme with  $(\alpha, \sigma) = (0.8, 0.4)$ .

	N	$\gamma = 3$		$\gamma = 2/\sigma$		$\gamma = 6$	
		$e(N)$	Rate	$e(N)$	Rate	$e(N)$	Rate
CN	80	3.65e-3	-	6.36e-4	-	5.07e-4	-
	160	1.59e-4	1.21	1.64e-4	1.99	1.25e-4	2.06
	320	6.90e-4	1.21	4.17e-5	2.00	3.07e-5	2.05
	640	3.01e-4	1.20	1.05e-5	2.00	7.50e-6	2.04
ESAV-CN	80	3.77e-3	-	7.56e-3	-	1.05e-2	-
	160	1.59e-4	1.26	2.00e-3	1.96	2.80e-3	1.95
	320	6.91e-4	1.21	5.16e-4	1.97	7.27e-3	1.97
	640	3.01e-4	1.20	1.31e-4	1.98	1.86e-4	1.98

# Numerical experiments

## Example 2

(*Energy stability*). Consider the TFSH model with  $g = 1$ ,  $\epsilon = 0.25$  and the initial value

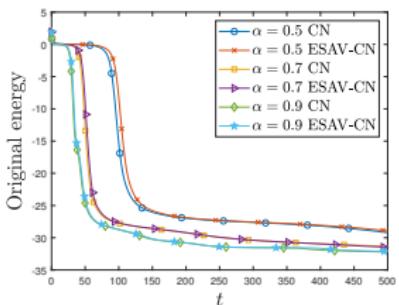
$$u_0(\mathbf{x}) = 0.07 - 0.02 \cos\left(\frac{\pi(x-12)}{16}\right) \sin\left(\frac{\pi(y-1)}{16}\right) \\ + 0.02 \cos^2\left(\frac{\pi(x+10)}{32}\right) \sin^2\left(\frac{\pi(y+3)}{32}\right) - 0.01 \sin^2\left(\frac{\pi x}{8}\right) \sin^2\left(\frac{\pi(y-6)}{8}\right).$$

in  $\Omega = (0, 32)^2$  until  $T = 500$ .

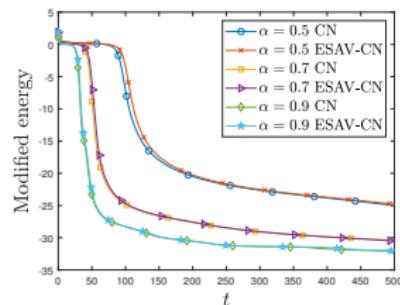
- Adaptive time strategy

$$\tau_{n+1} = \max\{\tau_*, r_\alpha(r_n)\tau_n\}, \quad \tau_* = \max \left\{ \tau_{\min}, \frac{\tau_{\max}}{\sqrt{1 + \lambda \|\partial_\tau u^n\|^2}} \right\} \quad (25)$$

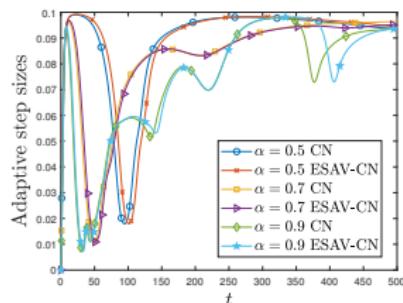
- $\tau_{\min} = 10^{-3}$ ,  $\tau_{\max} = 10^{-1}$ ,  $\lambda = 10^2$ .



(a) Original energy



(b) Modified energy



(c) Adaptive step-sizes

Figure 4: Energies of CN scheme and ESAV-CN scheme with different  $\alpha$ .

# Numerical experiments

Table 3: Comparisons of CN scheme and ESAV-CN scheme using adaptive strategy.

	$\alpha = 0.5$		$\alpha = 0.7$		$\alpha = 0.9$	
	Time step	CPU(s)	Time step	CPU(s)	Time step	CPU(s)
CN	6496	220.4	7574	215.6	8980	224.8
ESAV-CN	6477	92.6	7567	107.5	8959	126.2

# Outline

- 1 Background
- 2 Discrete gradient structure
- 3 Application to time fractional Swift-Hohenberg model
- 4 Application to time fractional sine-Gordon model
- 5 Conclusion

# Time fractional sine-Gordon model

- Consider the time fractional sine-Gordon (TFSG) model

$$\phi_t + \mathcal{I}^\beta \varsigma = 0, \quad (\mathbf{x}, t) \in \Omega \times (0, T] \quad (26)$$

subjected to the periodic boundary conditions.

- $\varsigma = \delta \mathcal{E}/\delta \phi$  with  $\mathcal{E}[\phi]$  defined by

$$\mathcal{E}[\phi] = \int_{\Omega} \frac{\epsilon}{2} |\nabla \phi|^2 + F(\phi) d\mathbf{x}, \quad \text{with } F(\phi) = 1 - \cos \phi. \quad (27)$$

- When  $\beta \rightarrow 1^-$ , the TFSG model recovers the classical sine-Gordon wave equation:  $\phi_{tt} = \epsilon \Delta \phi - \sin u$ , which satisfies

$$\frac{d}{dt} \left[ \mathcal{E}[\phi] + \frac{1}{2} \|\phi_t\|^2 \right] = 0.$$

# Variable-step CN scheme for TFSG model

- Using the integral averaged formula for Riemann-Liouville fractional integral, the variable-step CN scheme for TFSG model

$$\partial_{\tau} \phi^n + \mathcal{I}_{\tau}^{\beta} \bar{\zeta}^n = 0, \quad \text{with } \bar{\zeta}^n = -\epsilon \Delta \phi^{n-\frac{1}{2}} - \Psi(\phi^n, \phi^{n-1}), \quad (28)$$

where  $\Psi(\phi^n, \phi^{n-1}) = \frac{\cos \phi^n - \cos \phi^{n-1}}{\phi^n - \phi^{n-1}}$ .

- The variable-step CN scheme (28) is uniquely solvable when  $\tau_n \leq \sqrt[1+\beta]{\Gamma(2+\beta)}$ .

## Energy dissipation law of variable-step CN scheme

Taking the inner product of variable-step CN scheme (28) with  $\tau_n \bar{\varsigma}^n$ .

$$\begin{aligned}\langle \mathcal{I}_\tau^\beta \bar{\varsigma}^n, \tau_n \bar{\varsigma}^n \rangle &= \left\langle \sum_{j=1}^n c_{n-j}^{(\beta, n)} \tau_j \bar{\varsigma}^j, \tau_n \bar{\varsigma}^n \right\rangle \\ &= \mathcal{F}_\beta[\tau_n \bar{\varsigma}^n] - \mathcal{F}_\beta[\tau_n \bar{\varsigma}^{n-1}] + \mathcal{R}_\beta[\tau_n \bar{\varsigma}^n], \\ \langle \partial_\tau \phi^n, \tau_n \bar{\varsigma}^n \rangle &= \mathcal{E}[\phi^n] - \mathcal{E}[\phi^{n-1}].\end{aligned}$$

### Theorem 5

If the step-size ratio restriction (11) is satisfied, the variable-step CN scheme (28) preserves the following energy dissipation law

$$\partial_\tau \mathcal{E}_\beta[\phi^n] = -\frac{1}{\tau_n} \mathcal{R}_\beta[\tau_n \bar{\varsigma}^n], \quad \text{for } 1 \leq n \leq N, \quad (29)$$

where the modified energy  $\mathcal{E}_\beta[\cdot]$  is defined as

$$\mathcal{E}_\beta[\phi^n] = \mathcal{E}[\phi^n] + \mathcal{F}_\beta[\tau_n \bar{\varsigma}^n]. \quad (30)$$

# Asymptotic compatibility of variable-step CN scheme

- As  $\beta \rightarrow 1^-$ , the CN scheme (28) degrades into the CN scheme for the classical SG model

$$\partial_\tau \phi^n + \frac{\tau_n}{2} \bar{\varsigma}^n + \sum_{j=1}^{n-1} \tau_j \bar{\varsigma}^j = 0, \quad \text{for } n \geq 1,$$

which holds that

$$\hat{\mathcal{E}}[\phi^n] = \hat{\mathcal{E}}[\phi^{n-1}], \quad \text{for } n \geq 1, \tag{31}$$

where  $\hat{\mathcal{E}}[\phi^n] = \mathcal{E}[\phi^n] + \frac{1}{2} \left\| \sum_{j=1}^n \tau_j \bar{\varsigma}^j \right\|^2$ .

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- Moreover,  $\mathcal{E}_\beta[\phi^n] \rightarrow \hat{\mathcal{E}}[\phi^n]$ , and the **energy dissipation law** degrades into **conservation law** (31).

# Asymptotic compatibility of variable-step CN scheme

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$$\partial_\tau \phi^n + \frac{\tau_n}{2} \bar{\varsigma}^n + \sum_{j=1}^{n-1} \tau_j \bar{\varsigma}^j = 0, \quad \text{for } n \geq 1,$$

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- Moreover,  $\mathcal{E}_\beta[\phi^n] \rightarrow \hat{\mathcal{E}}[\phi^n]$ , and the energy dissipation law degrades into conservation law (31).
- Both discrete energy and energy dissipation law are asymptotically compatible

# Variable-step ESAV-CN scheme for TFSG model

- The variable-step ESAV-CN scheme based on the integral averaged formula

$$\partial_\tau \phi^n + \mathcal{I}_\tau^\beta \bar{\zeta}^n = 0, \quad (32a)$$

$$\bar{\zeta}^n = -\epsilon \Delta \phi^{n-\frac{1}{2}} + \eta(\bar{\phi}^{n-\frac{1}{2}}, \bar{r}^{n-\frac{1}{2}}), \quad (32b)$$

$$\ln r^n - \ln r^{n-1} = \left\langle \eta(\bar{\phi}^{n-\frac{1}{2}}, \bar{r}^{n-\frac{1}{2}}), \phi^n - \phi^{n-1} \right\rangle. \quad (32c)$$

where

$$r(t) = \exp(E_2(t)) = \exp\left(\int_{\Omega} 1 - \cos \phi d\mathbf{x}\right),$$

$$\eta(\phi, r) = \frac{r(t)}{\exp(E_2(t))} f(\phi).$$

# Energy dissipation law of variable-step ESAV-CN scheme

Taking the inner product of variable-step CN scheme (32a)–(32b) with  $\tau_n \bar{\varsigma}^n$ .

$$\langle \partial_\tau \phi^n, \tau_n \bar{\varsigma}^n \rangle = \frac{\epsilon}{2} \|\nabla \phi^n\|^2 - \frac{\epsilon}{2} \|\nabla \phi^{n-1}\|^2 + \ln r^n - \ln r^{n-1}.$$

$$\langle \mathcal{I}_\tau^\beta \bar{\varsigma}^n, \tau_n \bar{\varsigma}^n \rangle = \mathcal{F}_\beta[\tau_n \bar{\varsigma}^n] - \mathcal{F}_\beta[\tau_n \bar{\varsigma}^{n-1}] + \mathcal{R}_\beta[\tau_n \bar{\varsigma}^n].$$

## Theorem 6

Under the step-size ratio constraint (11), the variable-step ESAV-CN scheme (32) possesses the following energy dissipation law

$$\partial_\tau \tilde{\mathcal{E}}_\beta[\phi^n] = -\frac{1}{\tau_n} \mathcal{R}_\beta[\tau_n \bar{\varsigma}^n], \quad \text{for } 1 \leq n \leq N, \quad (33)$$

where the modified energy  $\tilde{\mathcal{E}}_\beta[\cdot]$  is defined as

$$\tilde{\mathcal{E}}_\beta[\phi^n] = \frac{\epsilon}{2} \|\nabla \phi^n\|^2 + \ln r^n + \mathcal{F}_\beta[\tau_n \bar{\varsigma}^n]. \quad (34)$$

Both discrete energy and energy dissipation law are asymptotically compatible

# Numerical experiments

## Example 3

(Convergence test). Consider the TFSG model with the initial value  $u_0(\mathbf{x}) = \pi \sin(2x) \sin(2y)$  in  $\Omega = (-3, 3)^2$  until  $T = 1$ ,  $\epsilon = 0.1$ .

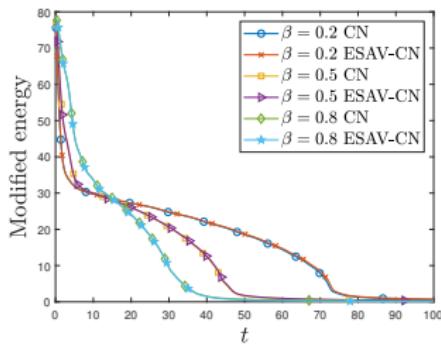
Table 4: Errors and convergence rates of CN scheme and ESAV-CN scheme with  $\beta = 0.3$ .

	N	$\gamma = 2$		$\gamma = 3$		$\gamma = 4$	
		$e(N)$	Rate	$e(N)$	Rate	$e(N)$	Rate
CN	20	4.07e-3	-	7.87e-3	-	1.28e-2	-
	40	1.09e-3	1.94	2.14e-3	1.95	3.56e-3	1.95
	80	2.87e-4	1.94	5.72e-4	1.94	9.63e-4	1.94
	160	7.52e-5	1.94	1.50e-4	1.95	2.56e-4	1.94
ESAV-CN	20	1.01e-2	-	1.99e-2	-	3.26e-2	-
	40	2.60e-3	1.99	5.28e-3	1.99	8.85e-3	1.99
	80	6.64e-4	1.99	1.40e-3	1.98	2.32e-3	1.99
	160	1.70e-4	1.98	3.51e-4	1.98	5.99e-4	1.98

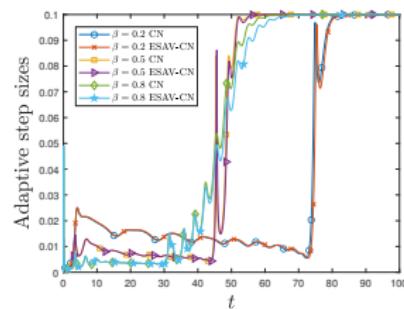
# Numerical experiments

## Example 4

(*Energy stability*). Take  $\Omega = (-10, 10)^2$  and  $\epsilon = 0.04$ . The initial value  $u_0(\mathbf{x}) = 4 \tanh \left[ \exp \left( 3 - \sqrt{x^2 + y^2} \right) \right]$ .



(a) Modified energy



(b) Adaptive step-sizes

Figure 5: Energies of CN scheme and ESAV-CN scheme with different  $\beta$ .

# Comparison

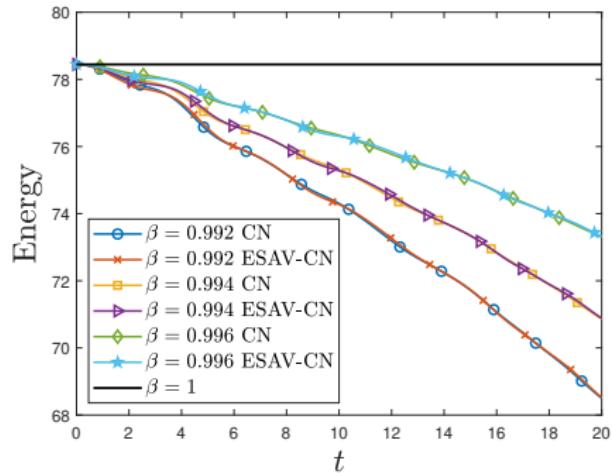


Figure 6: Modified energies of the proposed schemes for TFSG model and the original conservative energy of sine-Gordon model.

# Outline

- 1 Background
- 2 Discrete gradient structure
- 3 Application to time fractional Swift-Hohenberg model
- 4 Application to time fractional sine-Gordon model
- 5 Conclusion

# Conclusion

- A unified DGS for the nonuniform integral averaged formulae of time fractional derivative and integral.
- Theoretical framework of variable-step energy stable numerical schemes for fractional gradient flows and nonlinear integro-differential equations.
- SAV-type variable-step scheme and energy stability analysis.

**Future work:** extended to other gradient flows, such as TFCH, TFMBE model.

**Details:** Ren-jun Qi, Xuan Zhao, A unified design of energy stable schemes with variable steps for fractional gradient flows and nonlinear integro-differential equations, *SIAM J. Sci. Comput.*, to appear.

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*Thanks for your attention !*

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